

ROS

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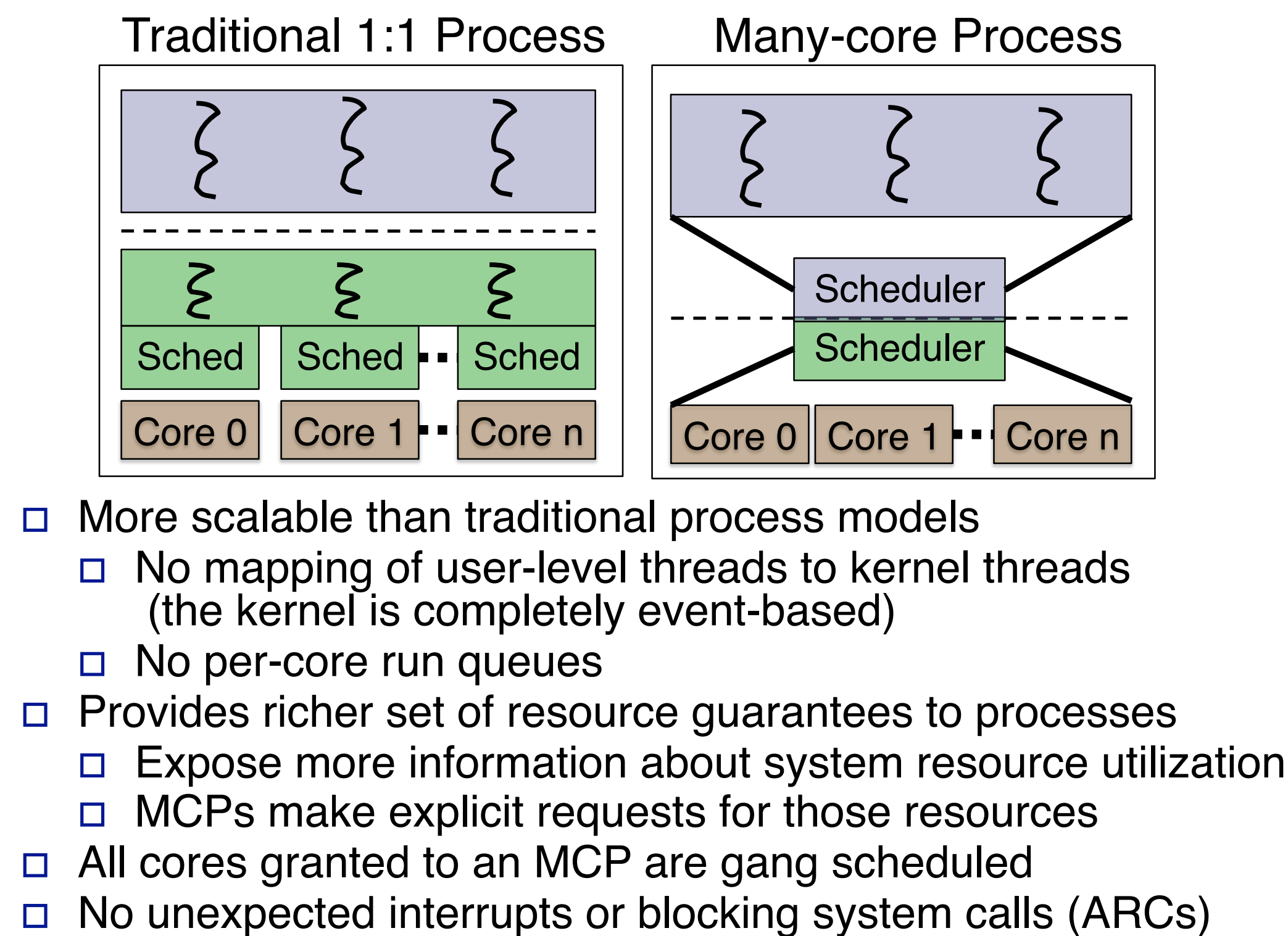
A. Waterman

A Scalable Operating System For Parallel Applications On Many-core Architectures

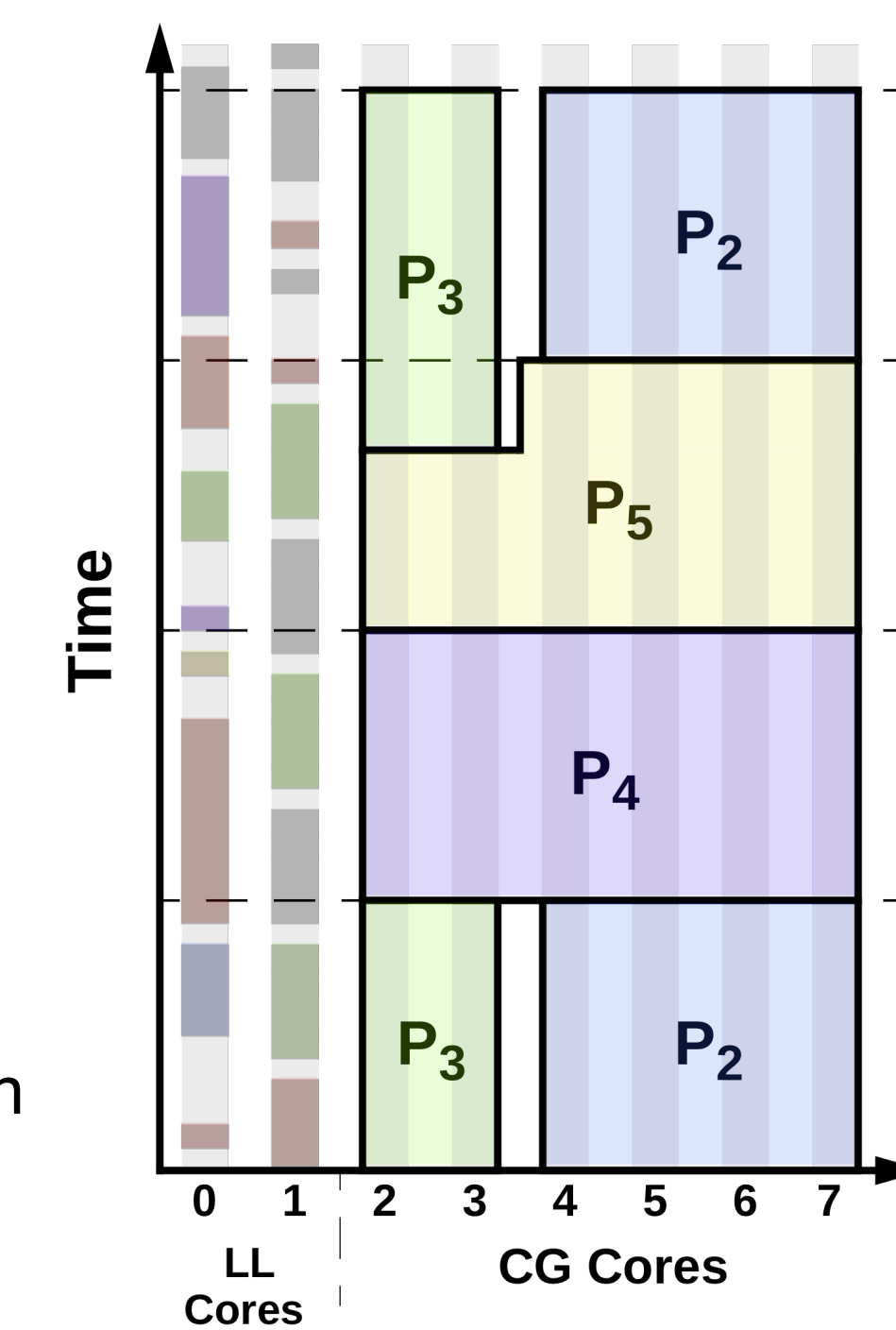
Design

- GOAL: Explicitly support parallel applications while improving kernel scalability
- Many-core Process (MCP)
 - No longer a single thread in a virtual processor
 - Multiple cores 'owned' by a single process
 - All cores gang scheduled
 - Information exposed up, requests sent down
- Asymmetric Use of Cores
 - Low-Latency vs. Coarse-Grained Cores
 - Asynchronous Remote Calls (ARCs)
 - Kernel control path on a limited number of cores
- Resource Provisioning
 - Provisions setup before allocation takes place
 - Increases isolation between processes
 - Enables predictable application performance
 - Allows the system to utilize unused resources

Many-Core Process

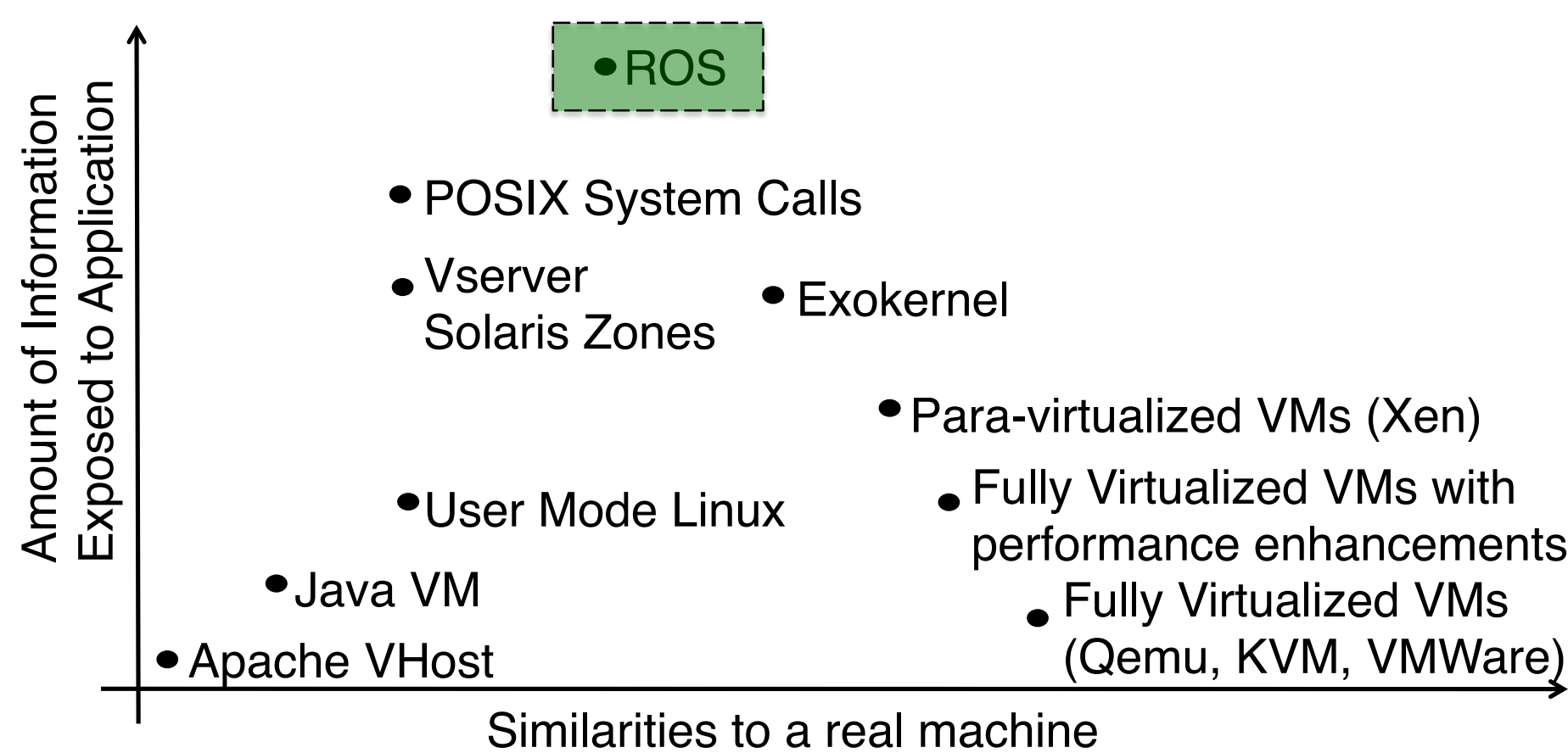


Asymmetric Use of Cores

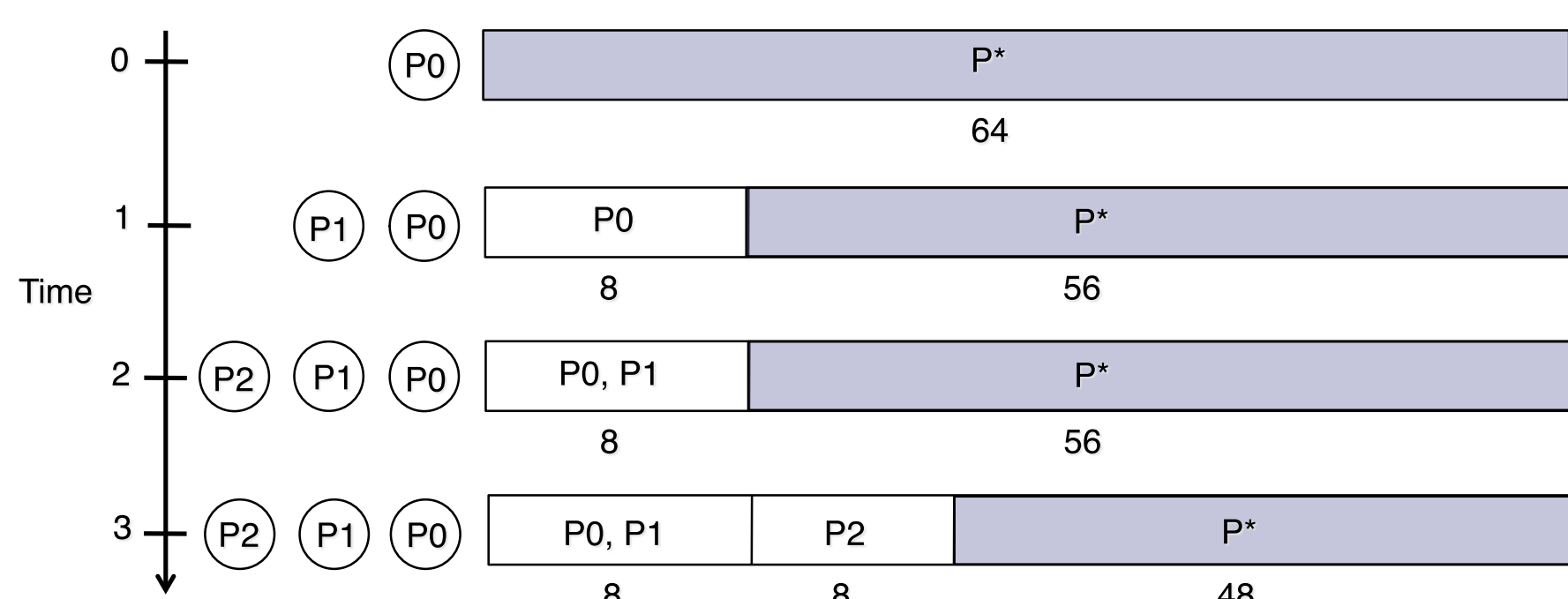


- Coarse-Grained Cores
 - Used for parallel computations requiring predictable performance
 - Time-sliced at coarse-granularity
 - Granted to apps running as MCPs
- Low-Latency Cores
 - Handle time-critical events out of band
 - Always runnable, not gang-scheduled
 - Time-sliced at fine-granularity
 - Examples: UI events, TCP ACKs, etc.
- Asynchronous Remote Calls (ARCs)
 - System calls serviced asynchronously on Low Latency Cores
 - Increase per core cache locality
 - Decrease cross core lock contention
 - Limit kernel interference with apps
 - Small set of cores control the system
 - Manages what processes run where
 - No need for per core run queues

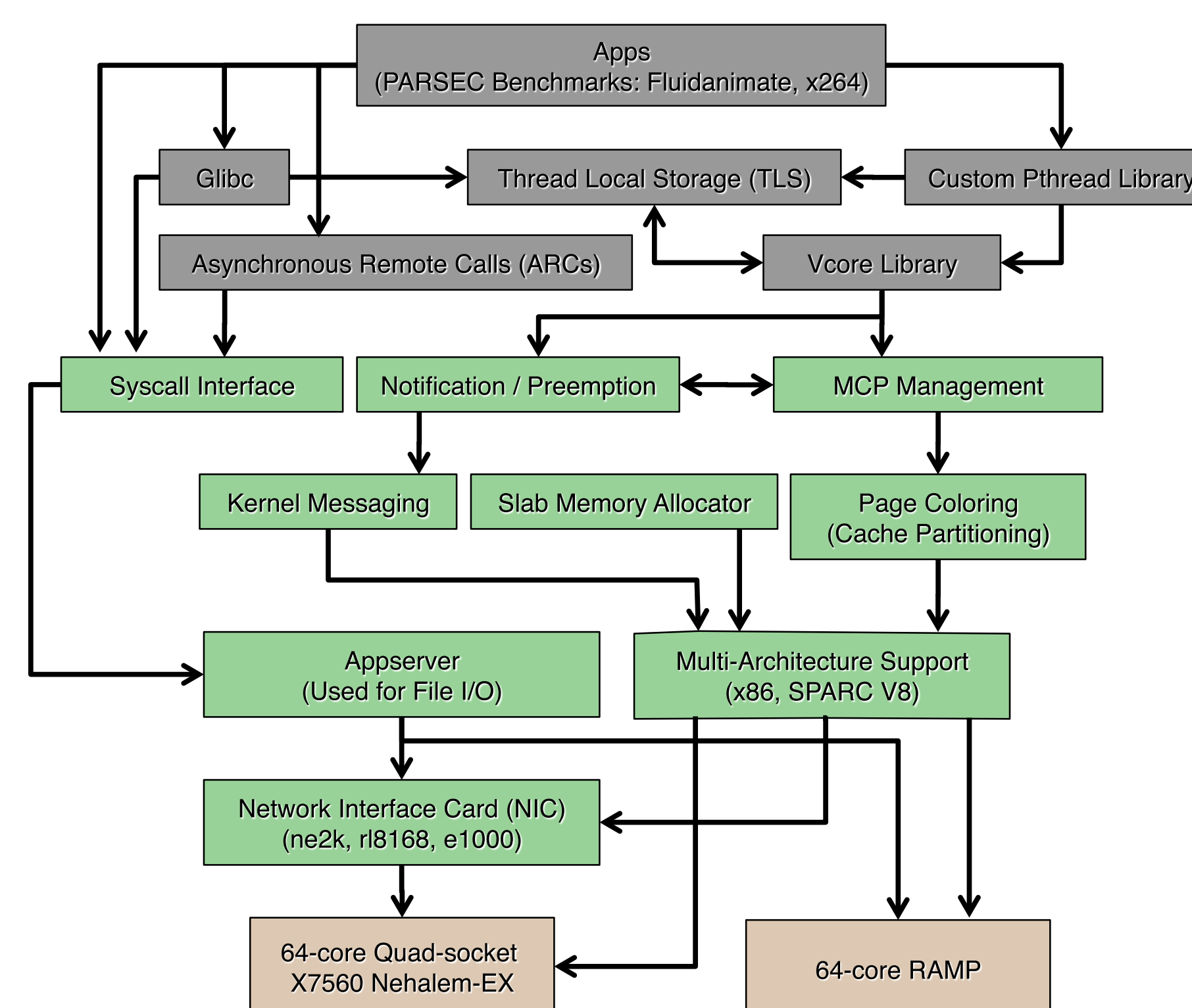
Resource Provisioning



- Resources **provisioned** to MCPs based on future needs
- Resources **allocated** to MCPs based on immediate needs
- Processes scheduled based on meeting resource guarantees (QoS)
- Resource guarantees enforced either in hardware or in software



Current Implementation



Preliminary Results

